

# MG995 伺服馬達(舵機)

程式代碼：

```
#include <Servo.h>    // Use Servo library,included with IDE

Servo myServo;       // Create Servo object to control the servo

void setup() {
  myServo.attach(9); // Servo is connected to digital pin 9
}

void loop() {
  myServo.write(180); // Rotate servo counter clockwise
  delay(2000);        // Wait 2 seconds
  myServo.write(0);   // Rotate servo clockwise
  delay(2000);
  myServo.write(90);  // Rotate servo to center
  delay(2000);
}
```